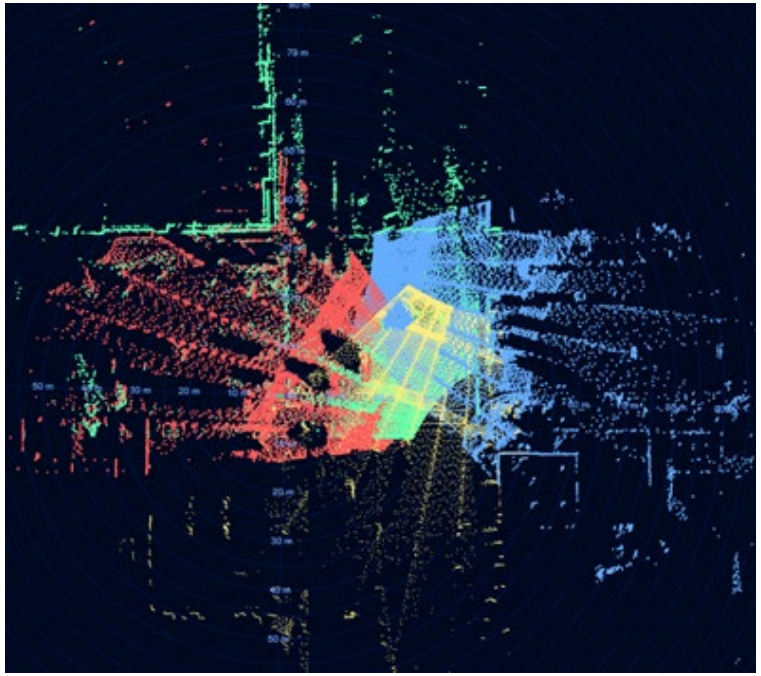
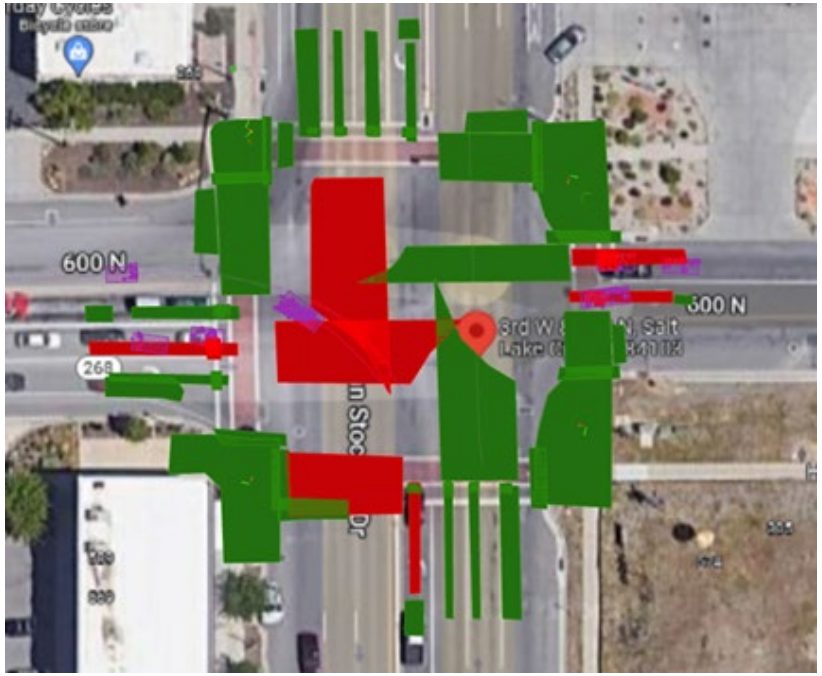
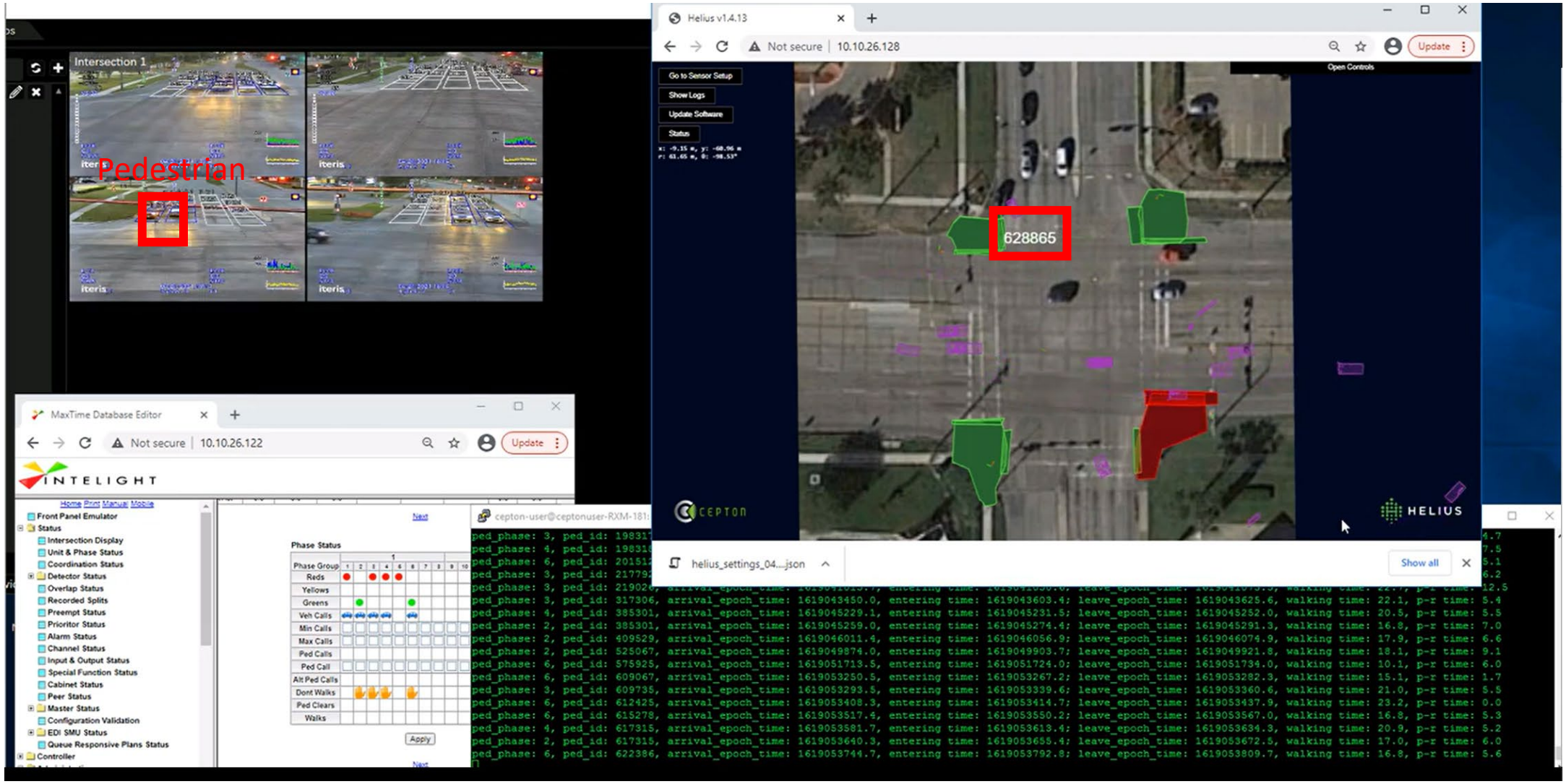
Current Project on LiDAR

- *Identifying near-misses (including red-light running) and reducing the conflict through D-FYA at signalized intersections using lidar sensors*



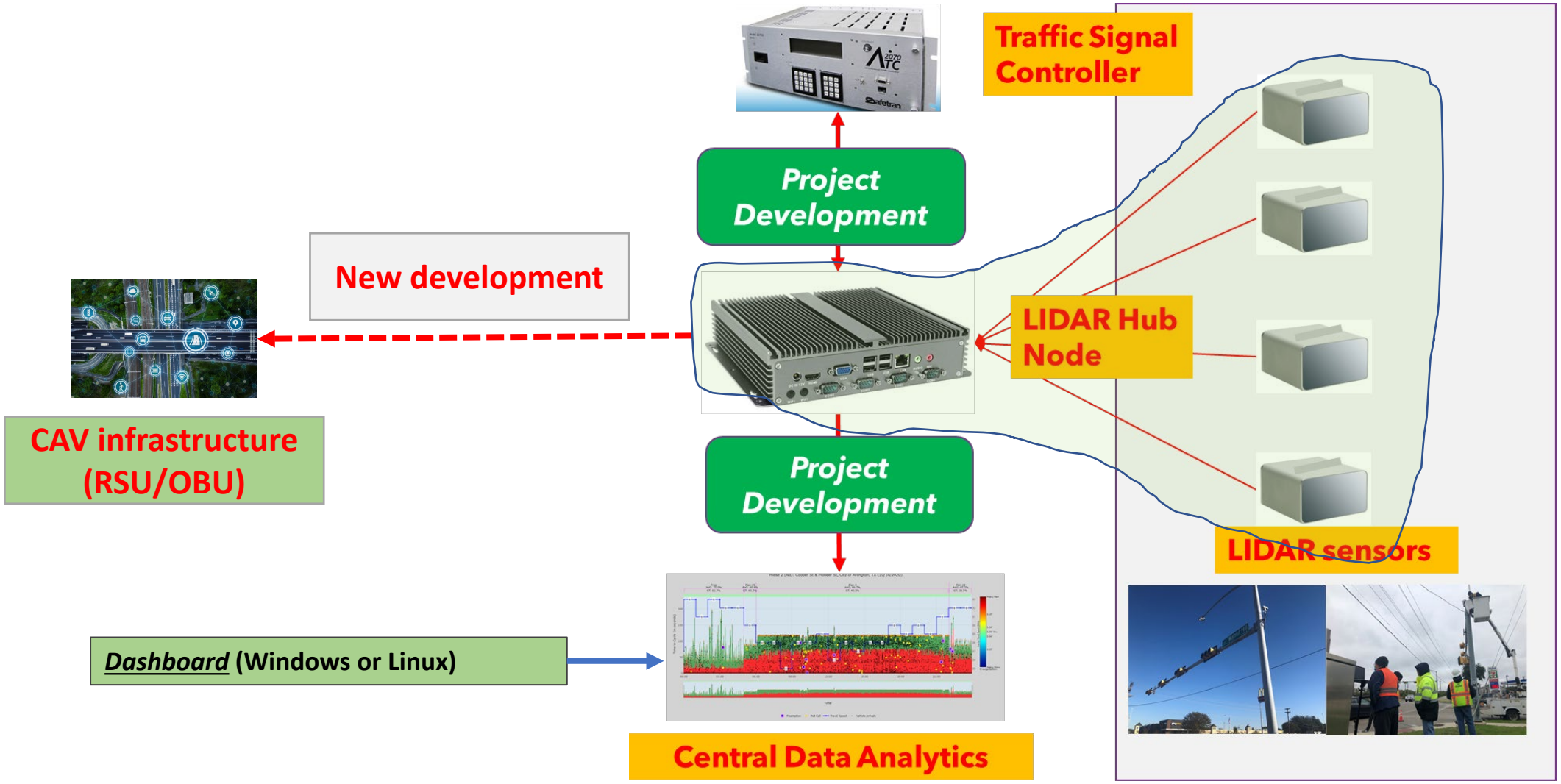


System in Operation

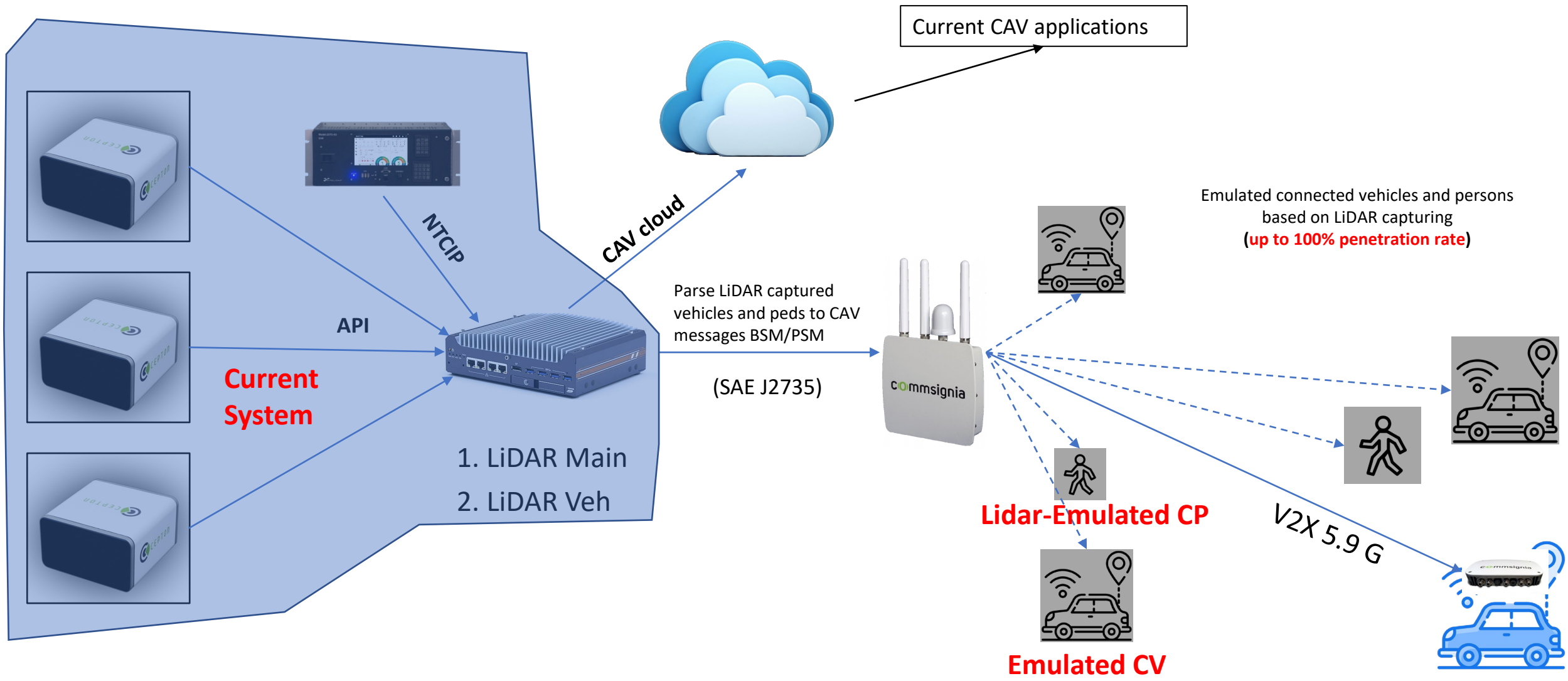


https://www.youtube.com/watch?v=tgi6Rzu_78k

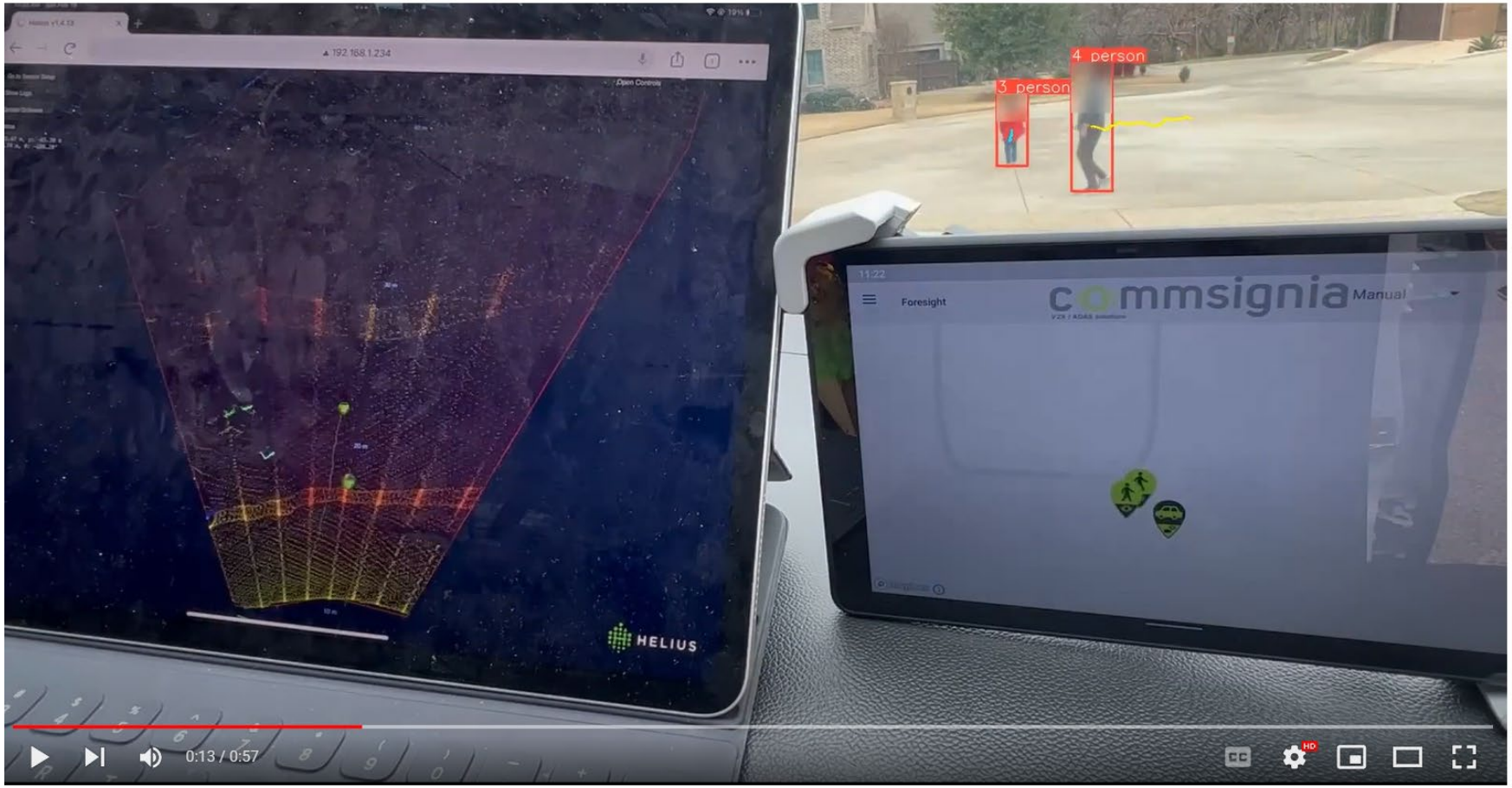
System Architecture



LiDAR + Signal + CAV



Lab Demo – Looking for local partners for field deployment



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